

# Scheduling multi-task applications on heterogeneous platforms

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# Outline

- 1 Framework
- 2 Theoretical study
  - Steady state scheduling
  - Off-line study
  - Extension
- 3 Experiments
- 4 Conclusion

# Bag-of-tasks Applications

## Bag of tasks

described by:

- the number of tasks
- the amount of computation of a task
- the amount of communication of a task
- their release date

On-line scheduling.

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- the number of **independent** tasks
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# Platform model



# Master-slaves platform

## The master

- Receive the bags of tasks
- Send the tasks to the processors
- Bounded multi-port model

## The processors

- Parallels
  - Identical
  - Uniform
- Related

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# Notations

## Tasks

- $n$  bags-of-tasks applications  $\mathcal{A}_k$
- $\mathcal{A}_i$  is composed of  $\Pi^{(i)}$  tasks.
- $w^{(i)}$ : amount of computation of a task of  $\mathcal{A}_i$
- $\delta^{(i)}$ : amount of communication of a task of  $\mathcal{A}_i$
- $r^{(i)}$ : release date of  $\mathcal{A}_i$
- $\mathcal{C}^{(i)}$ : completion time of  $\mathcal{A}_i$

# Notations

## Platform

- $p$  processors,
- $\mathcal{B}$ : bound of the multi-port model.
- $b_u$ : bandwidth of the link between the master and  $P_u$ ,
- $s_u$ : computational speed of worker  $P_u$ ,

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- $s_u^{(k)}$ : computational speed of related worker  $P_u$  with tasks of  $\mathcal{A}_k$ ,

# Objective

Scheduling the tasks to the processors in order to process this tasks

- according to the constraints,
  - of the processors
  - of the tasks
- optimizing an objective function

# Objective function

## Objective function

- Makespan

$$\max C^{(i)} \text{ or } C^{(max)}$$

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*Problem of satisfaction of the clients*

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$$\sum \{c^{(i)} - r^{(i)}\}$$

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*Problem of starvation*

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*Small applications can wait a long time*

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- Makespan
- Sum-flow
- Max-flow
- Max Stretch

$$\max \frac{C^{(i)} - r^{(i)}}{\text{Size of } \mathcal{A}_i}$$

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- Minimizing the makespan
- Maximizing the throughput
- Throughput of worker  $P_u$ :  $\rho_u^{*(0)}$
- Total throughput  $\rho^{*(0)} = \sum_{u=1}^p \rho_u^{*(0)}$

# Linear program

$$\left\{ \begin{array}{l} \text{MAXIMIZE } \rho^{*(0)} = \sum_{u=1}^p \rho_u^{*(0)} \\ \text{SUBJECT TO} \\ \rho_u^{*(0)} \frac{w^{(0)}}{s_u} \leq 1 \\ \rho_u^{*(0)} \frac{\delta^{(0)}}{b_u} \leq 1 \\ \sum_{u=1}^p \rho_u^{*(0)} \frac{\delta^{(0)}}{B} \leq 1 \end{array} \right. \quad (1)$$

Rational solution

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# Feasible schedule

Resource selection ( $\rho_u^{*(0)} = 0$ )

Master sends tasks to workers using the 1D-load balancing algorithm:

- the first worker to receive a task is the one with largest throughput
- each participating worker  $P_u$  has already received  $n_u$  tasks, the next worker to receive a task is chosen as the one minimizing

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# Back on multi-applications problem

Approximation of the best execution time:

$$MS^{*(k)} = \frac{\Pi^{(k)}}{\rho^{*(k)}}.$$

Real execution time:

$$C^{(k)} = r^{(k)} + MS^{(k)}$$

In general:

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$$S^k = \frac{MS^{(k)}}{MS^{*(k)}}$$

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- Binary search on the max-stretch
- For each candidate value  $S'$ , we know that:

$$\forall 1 \leq k \leq n, \frac{MS^{(k)}}{MS^{*(k)}} \leq S'$$

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# Deadlines

We set:

$$d^{(k)} = r^{(k)} + S' \times MS^{*(k)} \quad (2)$$

**Definition:** Epochal times

$$t^{(j)} \in \{r^{(1)}, \dots, r^{(n)}\} \cup \{d^{(1)}, \dots, d^{(n)}\}$$

, such that

$$t^{(j)} \leq t^{(j+1)}, \quad 1 \leq j \leq 2n - 1$$

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# Intervals

- run each application  $\mathcal{A}_k$  during its whole execution window  $[r^{(k)}, d^{(k)}]$ ,
- use a different throughput on each interval  $[t^{(j)}, t^{(j+1)}]$ ,  
 $r^{(k)} \leq t^{(j)}$  and  $t^{(j+1)} \leq d^{(k)}$ .

Notation:

- $\rho_u^{(k)}(j)$ : throughput achieved by  $\mathcal{A}_k$  during interval  $[t^{(j)}, t^{(j+1)}]$  on processor  $P_u$
- $\rho^{(k)}(j)$ : global throughput of  $\mathcal{A}_k$  during this period.

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# Linear program

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 \forall 1 \leq k \leq n, \sum_{\substack{[t^{(j)}, t^{(j+1)}] \\ t^{(j)} \geq r^{(k)} \\ t^{(j+1)} \leq d^{(k)}}} \rho^{(k)}(j) \times (t^{(j+1)} - t^{(j)}) = \Pi^{(k)} \\
 \forall 1 \leq k \leq n, \forall 1 \leq j \leq 2n - 1, \rho^{(k)}(j) = \sum_{u=1}^p \rho_u^{(k)}(j) \\
 \forall 1 \leq j \leq 2n - 1, \forall 1 \leq u \leq p, \sum_{k=1}^n \rho_u^{(k)}(j) \frac{w^{(k)}}{s_u^{(k)}} \leq 1 \\
 \forall 1 \leq j \leq 2n - 1, \forall 1 \leq u \leq p, \sum_{k=1}^n \rho_u^{(k)}(j) \frac{\delta^{(k)}}{b_u} \leq 1 \\
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# Algorithm

## Algorithm

- Computing all the  $MS^{*(k)}$ ,  $\forall 1 \leq k \leq n$
- Binary search on the max-stretch
- For each candidate stretch
  - compute the  $t^{(j)}$
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## Theorem

The previous scheduling algorithm finds the optimal max-stretch in polynomial time.

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The previous scheduling algorithm finds the optimal max-stretch in polynomial time.

# Proof (1/3)

## Part 1

A given max-stretch  $\mathcal{S}'$  is achievable if and only if the linear program has a solution

Consider an arbitrary solution that achieves  $\mathcal{S}'$ .

$\text{nb}(j, k, u)$  = number of tasks for  $\mathcal{A}_k$  on  $P_u$  during the interval  $[t^{(j)}, t^{(j+1)}]$ ,

Averaged throughput:

$$\bar{\rho}_u^{(k)}(j) = \frac{\text{nb}(j, k, u)}{t^{(j+1)} - t^{(j)}},$$

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$\{\bar{\rho}_u^{(k)}(j), \bar{\rho}^{(k)}(j)\}$  are a valid solution of the linear program:

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The first equation is satisfied:

$$\sum_{\substack{[t^{(j)}, t^{(j+1)}] \\ t^{(j)} \geq r^{(k)} \\ t^{(j+1)} \leq d^{(k)}}} \bar{\rho}^{(k)}(j) \times (t^{(j+1)} - t^{(j)}) =$$

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The second equation is satisfied by definition.

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The third equation is satisfied:

$$\sum_{k=1}^n \bar{\rho}_u^{(k)}(j) \frac{w^{(k)}}{s_u^{(k)}} = \sum_{k=1}^n \frac{nb(j, k, u)}{t^{(j+1)} - t^{(j)}} \cdot \frac{w^{(k)}}{s_u^{(k)}}$$

But we have

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A given max-stretch  $\mathcal{S}'$  is achievable if and only if the linear program has a solution

The fourth and fifth equations are satisfied as well.

Intuitively, the result comes from the linearity of linear programs!

# Proof (2/3)

## Part 2

The linear program can be solved in polynomial time.

- $2n - 1$  intervals, so  $O(n^2 + np)$  equations
- linear program over rational numbers,
- in theory using the ellipsoid method,
- in practice using standard software packages (glpk).

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- $\forall \mathcal{S}' \in [\mathcal{S}^1, \mathcal{S}^2]$ , the order of the  $t^{(i)}$  does not change
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New linear program:

$$\left\{ \begin{array}{l}
 \text{MINIMIZE } \mathcal{S}' \\
 \text{SUBJECT TO} \\
 \mathcal{S}^1 \leq \mathcal{S}' \leq \mathcal{S}^2 \\
 \forall 1 \leq k \leq n, \quad \sum_{[t^{(j)}(\mathcal{S}'), t^{(j+1)}(\mathcal{S}')] } \rho^{(k)}(j) \times (t^{(j+1)}(\mathcal{S}') - t^{(j)}(\mathcal{S}')) = \Pi^{(k)} \\
 \quad \quad \quad t^{(j)}(\mathcal{S}') \geq r^{(k)} \\
 \quad \quad \quad t^{(j+1)}(\mathcal{S}') \leq d^{(k)}(\mathcal{S}') \\
 \dots
 \end{array} \right.$$

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## Part 3

The binary search needs polynomial number of iterations.

The modified linear program has a solution if and only if a max-stretch  $\mathcal{S}' \in [\mathcal{S}^1, \mathcal{S}^2]$  is achievable.

At most  $n(n - 1)$  stretch intervals

# Proof (3/3)

## Part 3

The binary search needs polynomial number of iterations.

The modified linear program has a solution if and only if a max-stretch  $\mathcal{S}' \in [\mathcal{S}^1, \mathcal{S}^2]$  is achievable.

At most  $n(n - 1)$  stretch intervals

# Outline

- 1 Framework
- 2 Theoretical study
  - Steady state scheduling
  - Off-line study
  - **Extension**
- 3 Experiments
- 4 Conclusion

## On-line

Off-line algorithm at each release dates:

- For each application  $\mathcal{A}_k$ , count the number of tasks (if any) that have been executed
- update  $\Pi^{(k)}$
- update  $MS^{*(k)}$
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## Multi-level trees

- Resource constraints unchanged
- conservation law stating that for each application  $\mathcal{A}_k$  for each internal node

One-port model : previous constraint:

$$\sum_{u=1}^p \sum_{k=1}^n \rho_u^{(k)} \frac{\delta^{(k)}}{\mathcal{B}} \leq 1$$

Mixed-implementation of the two previous models

Return messages : for each application  $\mathcal{A}_k$

$$\delta^{(k)} \leftarrow \delta^{(k)} + \text{return}^{(k)}$$

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# The platform

## Hardware

Computers of the GDSDMI cluster:

- 8 SuperMicro servers 5013-GM, with processors P4 2.4 GHz;
- 5 SuperMicro servers 6013PI, with processors P4 Xeon 2.4 GHz;
- 7 SuperMicro servers 5013SI, with processors P4 Xeon 2.6 GHz;
- 7 SuperMicro servers IDE250W, with processors P4 2.8 GHz.
- 100Mbps Fast-Ethernet switch

# The tasks

## Software

- MPI communications
- Modification of slave parameters

## Tasks

Computation of matrices product

The linear programs are solved using `glpk`.

# The studied algorithms

- FIFO + Round-Robin
- FIFO + MCT
- S(R)PT + MCT
- S(R)PT + Demand-Driven
- Steady-state MWMA (Master Worker Multi-applications) on each time interval
- CBSSSM (Clever Burst Steady-State Stretch Minimizing)

# Results

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Eh wait!

You don't have any  
result yet !!

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# Conclusion

- Key points:
  - Realistic platform model
  - Optimal off-line algorithm
  - On-line algorithm

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- Key points:
  - Realistic platform model
  - Optimal off-line algorithm
  - On-line algorithm
- Extensions:
  - **Have some experimental results**
  - Consider other objective functions